

# Lecture 8

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## 1 Partially linear methods

A partially linear model is given by

$$f(x, z) = x^T \beta + g(z), \quad (x, z) \in \mathbf{R}^p \times \mathbf{R}^q,$$

where  $\beta \in \mathbf{R}^p$  is an unknown vector and  $g : \mathbf{R}^q \rightarrow \mathbf{R}$  is an unknown function. Note that the linear part does not contain an intercept, because it could not be identified separately from the unknown function  $g$ .

- An estimator for  $\beta$  is given by

$$\hat{\beta} = \left[ \sum_{i=1}^n \tilde{X}_i \tilde{X}_i^T \right]^{-1} \sum_{i=1}^n \tilde{X}_i \tilde{Y}_i, \quad (1)$$

where

$$\tilde{X}_i = X_i - \hat{X}_i, \quad \tilde{Y}_i = Y_i - \hat{Y}_i,$$

and  $\hat{X}_i$  is a kernel regression estimator for the conditional mean  $E[X | Z]$  evaluated at  $Z_i$ , and  $\hat{Y}_i$  is a kernel regression estimator for the conditional mean  $E[Y | Z]$  evaluated at  $Z_i$ . Since  $X \in \mathbf{R}^p$  is a vector, then  $\hat{X}_i \in \mathbf{R}^p$  is also a vector. Thus we have

$$\hat{X}_i = \hat{f}(Z_i), \quad \hat{f}(z) = \sum_{j=1}^n p_j(z) X_j,$$

where

$$p_j(z) = \frac{K_h(z - Z_j)}{\sum_{j=1}^n K_h(z - Z_j)}, \quad j = 1, \dots, n, \quad (2)$$

$K : \mathbf{R}^q \rightarrow \mathbf{R}$  is the kernel function,  $K_h(x) = K(x/h)/h^q$ , and  $h > 0$  is the smoothing parameter. Random variables  $\hat{Y}_i$  are defined similarly.

The estimator can be motivated by the facts that if we take conditional expectations of

$$Y = X^T \beta + g(Z) + \epsilon, \quad (3)$$

then we get

$$E(Y | Z) = E(X | Z)\beta + g(Z).$$

Subtracting, we get

$$Y - E(Y | Z) = (X - E(X | Z))^T \beta + \epsilon.$$

This linear regression model can be solved to get an estimator of  $\beta$ , but the unknown conditional expectations  $E(Y | Z)$  and  $E(X | Z)$  has to be estimated, and this has been done with kernel regression.

- From (3) we get

$$g(Z) = E(Y - X^T \beta | Z).$$

Inserting the estimator  $\hat{\beta}$  from (1) we can define an estimator for  $g$  as a kernel estimator

$$\hat{g}(z) = \sum_{i=1}^n p_i(z)(Y_i - X_i^T \hat{\beta}),$$

where  $p_i(z)$  are defined in (2).

## 2 Illustrations

We look at the following code

<http://cc.oulu.fi/~jklemela/finatool/>

(This is the same code as last time.)

```
# we obtain returns of the DAX stock index

ticker<-c("^GDAXI")
destfile<-"~/pois"
ry<-read.yahoo(ticker, source="web", destfile=destfile)
dm<-data.manip(ry,ticker)
method<-"return"
S<-returns(dm$data,method=method)
n<-length(S)
plot(S,type="l")
```

```

# we calculate volatilities for the 5 day periods

perlen<-5
pernum<-floor(n/perlen)
volas<-matrix(0,pernum,1)
for (i in 1:pernum){
  beg<-(i-1)*perlen+1
  end<-(i-1)*perlen+perlen
  period<-S[beg:end]
  volas[i]<-sqrt(sum(period^2)/perlen)*sqrt(252)
}
plot(volas,type="l")

# 1D case

# we try to predict the volatility of a 5 day period with the
# help of the volatility of the previous 5 day period

dendat<-matrix(0,pernum-1,2)
for (i in 1:(pernum-1)){
  dendat[i,1]<-volas[i]
  dendat[i,2]<-volas[i+1]
}
plot(dendat)

# we estimate the regression function

x<-matrix(dendat[,1],length(dendat[,1]),1)
y<-matrix(dendat[,2],length(dendat[,2]),1)
plot(x,y)

M<-2
m<-3
splitfreq<-1
t<-seq(0,1,0.05)
u<-matrix(0,length(t),1)
for (i in 1:length(t)) u[i]<-greedy(x,y,t[i],M,m,splitfreq)$val
matplot(x,y) #,add=TRUE)
matplot(t,u,type="l",add=TRUE,col="red")#xlim=c(0,1.1),ylim=c(0,1.1))

```

```

M<-10
m<-1
arg<-0.6
gr<-greedy(x,y,arg,M,m)
matplot(x,y)
matplot(gr$x,gr$y,add=TRUE,col="red")

# we make a logarithmic transform for the x-variable

x<-matrix(log(dendat[,1]),length(dendat[,1]),1)
y<-matrix(dendat[,2],length(dendat[,2]),1)
plot(x,y)

M<-2
m<-5
splitfreq<-1
t<-seq(-3.5,0.1,0.05)
u<-matrix(0,length(t),1)
for (i in 1:length(t)) u[i]<-greedy(x,y,t[i],M,m,splitfreq=splitfreq)$val
matplot(x,y) #,add=TRUE)
matplot(t,u,type="l",add=TRUE,col="red")#xlim=c(-3.5,0.1),ylim=c(0,1.1))

# 2D case

# we use now the volatilities of two periods to predict
# the volatility of the next period

dendat<-matrix(0,pernum-2,3)
for (i in 1:(pernum-2)){
  dendat[i,1]<-volas[i]
  dendat[i,2]<-volas[i+1]
  dendat[i,3]<-volas[i+2]
}
plot(dendat[,1],dendat[,2])

library(scatterplot3d)
scatterplot3d(dendat)

# we make the logarithmic transform for the explanatory variables
# and estimate the regression function

```

```

x<-matrix(0,dim(dendat)[1],2)
x[,1]<-log(dendat[,1])
x[,2]<-log(dendat[,2])
plot(x)
y<-dendat[,3]
scatterplot3d(x[,1],x[,2],y)

M<-5
m<-5
t<-seq(-3.5,0.1,0.1)
u<-t
z<-matrix(0,length(t),length(u))
for (i in 1:length(t))
  for (j in 1:length(u))
    z[i,j]<-greedy(x,y,c(t[i],u[j]),M,m)$val

contour(t,u,z) #,drawlabels=FALSE)

persp(t,u,z,phi=30,theta=30)

```

### 3 Examination

A possible question in the examination:

7) Let

$$Y = X^T \beta + g(Z) + \epsilon$$

be a partially linear model. Assume that we have data

$$(Y_1, X_1, Z_1), \dots, (Y_n, X_n, Z_n)$$

generated from the partially linear model. Assume that we have an estimator  $\hat{\beta}$  for  $\beta$ . Construct an estimator for  $g$ .